SYDE 312 NUMERICAL METHODS - FINAL EXAM

6 April 2004, 2:00-5:00

INSTRUCTIONS:

1. Aids allowed:

- Any written material (text, notes, etc.)
- Computer with Matlab, Excel, and other computational software available, including installed help systems
- You may use the local C: drive to save m-files created during the exam period if you wish
- Calculator
- 2. Aids NOT ALLOWED:
 - External communication (internet, email etc.)
 - Access to previously-prepared computer files (N:drive etc.)
- 3. Read the questions CAREFULLY.
- 4. Each question is allocated an EQUAL number of marks. Answer as many as you can in the time provided.
- 5. Provide sufficient details in your solution to demonstrate that you can apply whatever method is being used. DO NOT simply give a Matlab-derived answer, unless specifically given that option in the question.
- 6. Complete one blank front page with your personal information (NAME, ID).
- 7. Write your solutions on the answer pages provided, using both sides, and at least one complete side for each question. DO NOT MIX QUESTIONS ON ANY SIDE.
- 8. On each answer page side write the question number you are answering and your name in the spaces provided.
- 9. At the end of the exam you will assemble your pages, with the blank ID page in front on top. Have them ready to be stapled together as they are collected.

- - (a) Find a 4th degree Newton interpolating polynomial for this data.
 - (b) Use Matlab (or otherwise) to find the equations for the piecewise cubic splines that interpolate the given data with knot-a-knot end conditions.
 - (c) Sketch a plot of the curves you obtained in (a) and (b), clearly indicating where/how they differ.
 - (d) Determine estimated values for the derivative f'(5) using the two interpolating functions in parts (a) and (b). Why are the values different?
- 2. Solve the initial value problem

$$y' = \frac{3x}{y} - xy, y(0) = 2$$

over the interval [0, 1].

- (a) Use the explicit midpoint method with step size 0.5
- (b) Use the Runge-Kutta 4th order method with step size 0.5
- (c) Use an appropriate Matlab ode solver.
- (d) Provide a sketch plot showing clearly the solution curve from part (c), and the (x, y)-values you obtained in parts (a) and (b).

3. Consider the linear system Ax = b with $A = \begin{bmatrix} 4 & 2 & 1 \\ 1 & 3 & 1 \\ 1 & 1 & 4 \end{bmatrix}$ and $b = \begin{bmatrix} 3 & -1 & 4 \end{bmatrix}^T$.

- (a) Is A positive-definite?
- (b) Obtain an exact solution to the system using the quickest method (you may simply give a Matlab answer here if you wish, but explain how you obtained it).
- (c) Apply SIX iterations of the Gauss-Seidel method with a starting vector $\begin{bmatrix} 0 & 0 & 0 \end{bmatrix}^T$.
- (d) Determine the 2-norm absolute error at each stage in the iteration process of part (c), comparing the current solution to the exact solution obtained in part (b).
- (e) Sketch a plot of the absolute error values you found in part (d) against the iteration number.
- 4. (a) Why is Gaussian-quadrature able to achieve such good accuracy with a small number of function evaluations? Are there any functions for which a Newton-Cotes rule might be better?
 - (b) Provide a sketch plot of the function $f(x) = (1 + e^x)^{-2}$ over the interval [0,3].

- (c) Use 3-point Gauss-Legendre quadrature to evaluate the integrals: $\int_0^3 f(x)dx$, $\int_0^{30} f(x)dx$, and $\int_0^{300} f(x)dx$. [3-point Nodes: $-\sqrt{3/5}, 0, \sqrt{3/5}$; Weights: 5/9, 8/9, 5/9.]
- (d) Evaluate the integral $\int_0^\infty f(x) dx$ using 3-point Gauss-Laguerre quadrature. [Nodes: 0.41577455678348, 2.29428036027904, 6.28994508293748; Weights: 0.71109300992917, 0.27851773356924, 0.01038925650159]
- (e) Explain why the sequence of integrals obtained using Gauss-Legendre quadrature fails to converge to the value obtained in part (e).
- 5. For the function $f(x) = e^x + x^2 5x$:
 - (a) Use a Matlab plot to estimate the location of the two roots.
 - (b) Locate the smaller root to an accuracy of at least six decimals using fixed-point iteration.
 - (c) Give the result of a test which predicts the failure of fixed point iteration when attempting to find the other root.
 - (d) Find the other root accurate to at least six decimals using Newton's method.
 - (e) Provide a sketch plot of the function, indicating the two roots you found above.

6. Consider the linear system
$$Ax = b$$
 with $A = \begin{bmatrix} 2 & 4 & 1 \\ 5 & 2 & 1 \\ 1 & 2 & 1 \end{bmatrix}$ and $b = \begin{bmatrix} -5 & 12 & 3 \end{bmatrix}^T$.

- (a) Use Matlab, or otherwise, to find an LU-factorization with partial pivoting for the matrix A, i.e. matrices L, U and a permutation matrix P, so that PA = LU.
- (b) Use the factorization of part (a) to obtain (by hand) the exact solution to the system.
- (c) The vector $\hat{x} = \begin{bmatrix} 2 & -5 & 12 \end{bmatrix}^T$ is an approximate solution to the system. Apply iterative improvement to this \hat{x} and attempt to obtain the solution you found in part (b).
- - (a) Linearize the data with the transformation $Y = \ln(y)$ and find a least-squares fit of the form $f(x) = ce^{ax}$. Give the normal equations and solve them using a QRfactorization (which you can obtain with Matlab if you wish).
 - (b) Linearize the data with the transformation $Y = y^{-1/2}$ and find a least-squares fit of the form $f(x) = (ax + b)^{-2}$. Give the normal equations and solve them using the SVD (which you can obtain with Matlab if you wish).
 - (c) Determine which of the fitting functions above is better, by evaluating the residuals with respect to the original data.